

# Stochastic differential Equations to model fishing vessels displacements

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# Fisheries Context

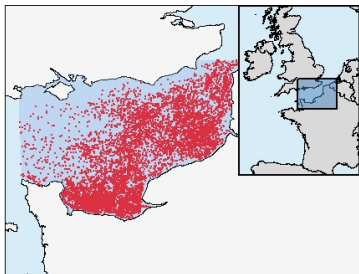


## Modeling vessels displacement to

- Understand the spatial mechanisms of fishing effort;
- Getting indirect information over target species;
- Anticipate fishermen's reaction to management measure.

# Case of study

## GPS pings



## Data Characteristics

- Mandatory Vessel Monitoring System (VMS);
- *Zone of interest* : Eastern Channel;
- All french bottom trawlers > 12 m;
- One ping every 1 or two hours (mostly irregular);
- 5 years of data.

# Mathematical framework

## Modeling objectives

- Dealing with irregularity in data;
- Dealing with a spatially explicit model;
- Having a general mathematical framework to express the movement.

## Equations of the movement

- The position process  $(X_t)_{t \geq 0}$  of a vessel is supposed to be the solution of a time homogeneous Stochastic Differential Equation (SDE)

$$dX_t = b(X_t)dt + \gamma(X_t)dW_t$$

where  $W_t$  is the standard Wiener process.

- The drift  $(b(X_t, t) : \mathbb{R}^2 \mapsto \mathbb{R}^2)$  and the diffusion  $(\gamma(X_t, t) : \mathbb{R}^2 \mapsto \mathbb{R}^2)$  satisfy certain regularity conditions

# Parametric form for $b(X_t)$ and $\gamma(X_t)$

## The diffusion part

- In a first approach, the diffusion part is assumed to be constant

$$\gamma(X_t) = \Gamma$$

## The drift part

- Following Brillinger (2009), the drift is assumed to be the gradient of a potential

$$b(X_t) = -\nabla P(X_t)$$

where  $P(X_t) : \mathbb{R} \mapsto \mathbb{R}^2$  is the **potential function**, and  $\nabla$  is the gradient operator;

- This writing leads to an intuitive interpretation of the drift, which is the direction towards attractive zones.

## Parametric form for $b(X_t)$ (2)

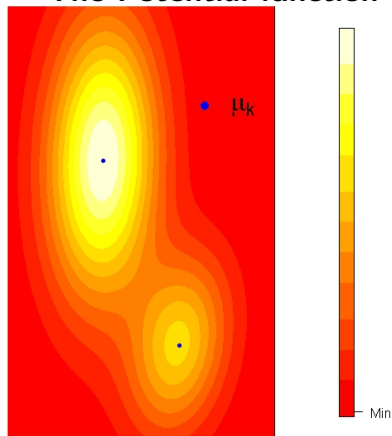
### The potential function

- We pose  $P(x) := \sum_{k=1}^K \pi_k \varphi_k(x)$
- $\varphi_k$  being the probability density function of a 2 dimensional Gaussian random vector with mean  $\mu_k$  and covariance matrix  $C_k$
- $\pi_k$  being the weight of the  $k$ th Gaussian component of the mixture.
- Thus, by definition of  $b(x)$  we have

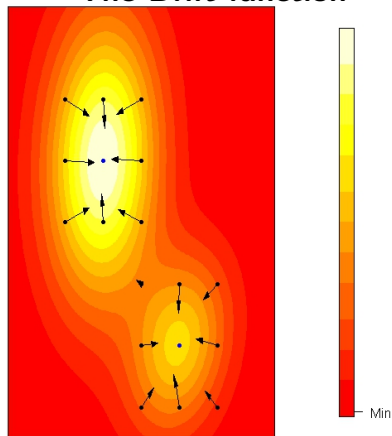
$$b(x) = \sum_{k=1}^K \pi_k \varphi_k(x) C_k^{-1} (x - \mu_k)$$

# Parametric form for $b(X_t)$ , example

## The Potential function



## The Drift function



# Simulation of SDEs

## How to draw a process from the p.d.f of our SDE solution?

### Two possible approaches

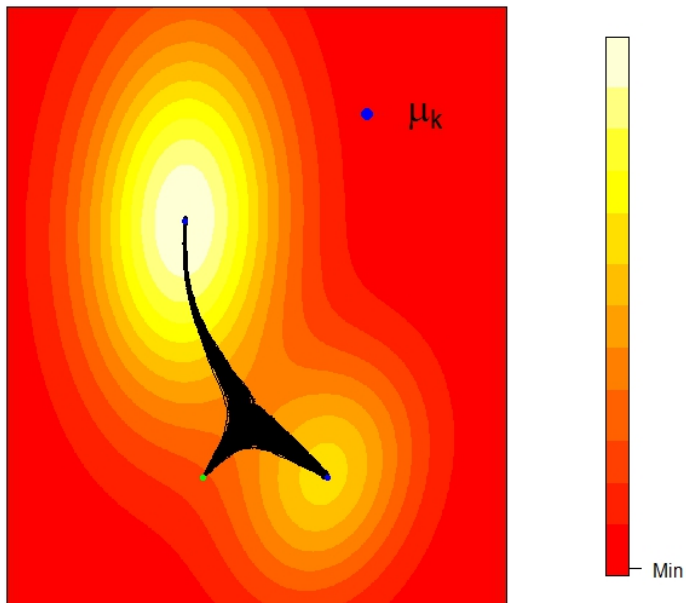
- **Discrete Schemes:** Samples are obtained from *approximation* (at regular discrete time steps) of the targeted p.d.f (e.g. Euler or Milstein scheme)
- **Exact Algorithm (EA):** Given some restrictions on  $b(\cdot)$  and  $\gamma(\cdot)$ , samples are obtained from the *exact* targeted p.d.f.

### Choice made for our model

- The  $b(\cdot)$  and  $\gamma(\cdot)$  described above satisfy the EA conditions.
- Simulations of processes are done using EA, avoiding an approximation of the targeted p.d.f.



# Simulations Examples 1000 simulations



# Estimation

## Goal of the estimation

- Estimating Utilization Distribution parameters :  
 $\Theta = \{\pi_k, \mu_k, C_k\}$
- Estimating diffusion parameter  $\Gamma$
- The likelihood is then needed to be maximized.

## Inference technique

- We can simulate from the targeted distribution;
- We don't have analytical expression of the likelihood
- A MCEM approach is adopted to maximize the likelihood.
- Work still in progress...

# Conclusions and perspectives

## Conclusions so far

- This general model seems promising to model movement;
- Allows to gather Utilization distribution concept and movement models.
- A challenging but not straightforward mathematical framework

## Short term perspectives

- Application to our case of study
- Comparison with other methods to obtain UD.

## Longer term perspectives

- Introducing environmental covariates in the drift function
- Introducing time heterogeneity

## Some references



Brillinger, D. **Modelling Spatial Trajectories**, chp 26 in *HANDBOOK OF SPATIAL STATISTICS*, 2010, CRC Press.



Beskos, A., Papaspiliopoulos, O., Roberts, G.O. and Fearnhead, P. **Exact and computationally efficient likelihood-based estimation for discretely observed diffusion processes**, 2006, *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*.

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